



PWM Current Control Type Stepping Motor Driver

Preliminary

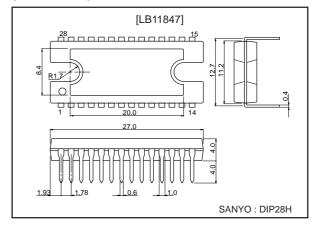
Overview

The LB11847 is a driver IC for stepping motors with PWM current control bipolar drive (fixed OFF time). A special feature of this IC is that V_{REF} voltage is constant while the current can be set in 15 steps, allowing drive of motors ranging from 1-2 phase exciter types to 4W 1-2 phase exciter types. The current decay pattern can also be selected (SLOW DECAY, FAST DECAY, MIX DECAY) to increase the decay of regenerative current at chopping OFF, thereby improving response characteristics. This is especially useful for carriage and paper feed stepping motors in printers and similar applications where high-precision control and low vibrations are required.

Package Dimensions

unit: mm

3147B-DIP28H



Features

- PWM current control (fixed OFF time)
- Load current digital selector (1-2, W1-2, 2W1-2, 4W1-2 phase exciter drive possible)
- Selectable current decay pattern (SLOW DECAY, FAST DECAY, MIX DECAY)
- Simultaneous ON prevention function (feedthrough current prevention)
- Noise canceler
- · Built-in thermal shutdown circuit
- Built-in logic low-voltage OFF circuit

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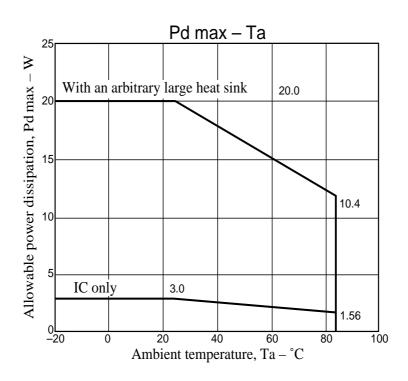
Specifications

Absolute Maximum Ratings at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Motor supply voltage	V _{BB}		50	V
Output peak current	I _{OPEAK}	t _W ≤ 20 μs	1.75	Α
Output continuous current	I _O max		1.5	А
Logic supply voltage	V _{CC}		7.0	V
Logic input voltage range	V _{IN}		-0.3 to V _{CC}	V
Emitter output voltage	V _E		1.0	V
Allowable power dissipation	Pd max	Ta = 25°C	3.0	W
		With heat sink	20	W
Operating temperature	Topr		-20 to +85	င္
Storage temperature	Tstg		-55 to +150	Ç

Allowable Operating Ranges at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Motor supply voltage range	V _{BB}		10 to 45	V
Logic supply voltage range	V _{CC}		4.75 to 5.25	V
Reference voltage range	V _{REF}		0.0 to 3.0	V



LB11847

Electrical Characteristics at Ta = 25 °C, V_{BB} = 45V, V_{CC} = 5V, V_{REF} = 1.52V

Parameter	Symbol	Conditions		Ratings			
raiametei	Symbol	Conditions	min	typ	max	Unit	
[Output Block]							
Output stage supply voltage	I _{BB ON}		2.3	3.5	5.0	mA	
	I _{BB OFF}		0.5	0.8	1.1	mA	
Output saturation voltage	V _O (sat)1	I _O = +1.0A, sink		1.2	1.6	V	
	V _O (sat)2	I _O = +1.5A, sink		1.5	1.9	V	
	V _O (sat)3	I _O = −1.0A, source		1.9	2.2	V	
	V _O (sat)4	I _O = −1.5A, source		2.2	2.4	V	
Output leak current	I _O (leak)1	$V_O = V_{BB}$, sink			50	μΑ	
	I _O (leak)2	V _O = 0V, source	-50			μΑ	
Output sustain voltage	V _{SUS}	L = 15 mH, I _O = 1.5A, Guaranteed design value	45			V	
[Logic Block]							
Logic supply voltage	I _{CC ON}	I ₄ = 2.0V, I ₃ = 2.0V, I ₂ = 2.0V, I ₁ = 2.0V	19.5	26	36.5	mA	
	I _{CC OFF}	ENABLE = 2.0V	10.5	15	19.5	mA	
Input voltage	V _{IH}		2.0			V	
	V _{IL}				0.8	V	
Input current	l _{IH}	V _{IH} = 2.0V			100	μΑ	
	I _{IL}	V _{IL} = 0.8V	-10			μΑ	
Sensing voltage	V _E	I ₄ = 2.0V, I ₃ = 2.0V, I ₂ = 2.0V, I ₁ = 2.0V	0.470	0.50	0.525	V	
		I ₄ = 2.0V, I ₃ = 2.0V, I ₂ = 2.0V, I ₁ = 0.8V	0.445	0.48	0.505	V	
		I ₄ = 2.0V, I ₃ = 2.0V, I ₂ = 0.8V, I ₁ = 2.0V	0.425	0.46	0.485	V	
		I ₄ = 2.0V, I ₃ = 2.0V, I ₂ = 0.8V, I ₁ = 0.8V	0.410	0.43	0.465	V	
		I ₄ = 2.0V, I ₃ = 0.8V, I ₂ = 2.0V, I ₁ = 2.0V	0.385	0.41	0.435	V	
		I ₄ = 2.0V, I ₃ = 0.8V, I ₂ = 2.0V, I ₁ = 0.8V	0.365	0.39	0.415	V	
		I ₄ = 2.0V, I ₃ = 0.8V, I ₂ = 0.8V, I ₁ = 2.0V	0.345	0.37	0.385	V	
		I ₄ = 2.0V, I ₃ = 0.8V, I ₂ = 0.8V, I ₁ = 0.8V	0.325	0.35	0.365	V	
		I ₄ = 0.8V, I ₃ = 2.0V, I ₂ = 2.0V, I ₁ = 2.0V	0.280	0.30	0.325	V	
		I ₄ = 0.8V, I ₃ = 2.0V, I ₂ = 2.0V, I ₁ = 0.8V	0.240	0.26	0.285	V	
		I ₄ = 0.8V, I ₃ = 2.0V, I ₂ = 0.8V, I ₁ = 2.0V	0.195	0.22	0.235	V	
		I ₄ = 0.8V, I ₃ = 2.0V, I ₂ = 0.8V, I ₁ = 0.8V	0.155	0.17	0.190	V	
		I ₄ = 0.8V, I ₃ = 0.8V, I ₂ = 2.0V, I ₁ = 2.0V	0.115	0.13	0.145	V	
		I ₄ = 0.8V, I ₃ = 0.8V, I ₂ = 2.0V, I ₁ = 0.8V	0.075	0.09	0.100	V	
Reference current	I _{REF}	V _{REF} = 1.5V	-0.5			μΑ	
CR pin current	I _{CR}	CR = 1.0V	-4.6		-1.0	mA	
MD pin current	I _{MD}	MD = 1.0V, CR = 4.0V	-5.0			μΑ	
DECAY pin current Low	I _{DECL}	V _{DEC} = 0.8V	-10			μΑ	
DECAY pin current High	I _{DECH}	V _{DEC} = 2.0V			5	μΑ	
Thermal shutdown temperature	TSD			170		°C	
Logic ON voltage	L _{VSD} 1		3.35	3.65	3.95	V	
Logic OFF voltage	L _{VSD} 2		3.20	3.50	3.80	V	
L _{VSD} hysteresis width	ΔL _{VSD}		0.065	0.15	0.23	V	

Truth Table

PHASE	ENABLE	OUT _A	OUTĀ
Н	L	Н	L
L	L	L	Н
	Н	OFF	OFF

Set Current Truth Table

I _A 4	I _A 3	I _A 2	I _A 1	Set current I _{OUT}	Current ratio (%)
1	1	1	1	$11.5/11.5 \times V_{REF}/3.04RE = I_{OUT}$	100
1	1	1	0	11.0/11.5 × V _{REF} /3.04RE = I _{OUT}	95.65
1	1	0	1	$10.5/11.5 \times V_{REF}/3.04RE = I_{OUT}$	91.30
1	1	0	0	$10.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	86.95
1	0	1	1	$9.5/11.5 \times V_{REF}/3.04RE = I_{OUT}$	82.61
1	0	1	0	$9.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	78.26
1	0	0	1	$8.5/11.5 \times V_{REF}/3.04RE = I_{OUT}$	73.91
1	0	0	0	$8.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	69.56
0	1	1	1	$7.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	60.87
0	1	1	0	$6.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	52.17
0	1	0	1	$5.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	43.48
0	1	0	0	$4.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	34.78
0	0	1	1	$3.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	26.08
0	0	1	0	$2.0/11.5 \times V_{REF}/3.04RE = I_{OUT}$	17.39

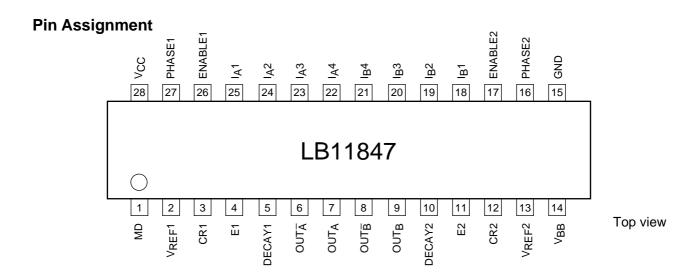
^{*} Current ratio (%) is the calculated set current value.

Current Decay Switching Truth Table

Current decay mode	DECAY pin	MD pin	Output chopping
SLOW DECAY	ECAY H L		Upper-side chopping
FAST DECAY	L	L L Dual-side ch	
MIX DECAY	1	4V to 1.5V input	CR voltage > MD : dual-side chopping
IVIIA DECAT	_	voltage setting	CR voltage < MD : upper-side chopping

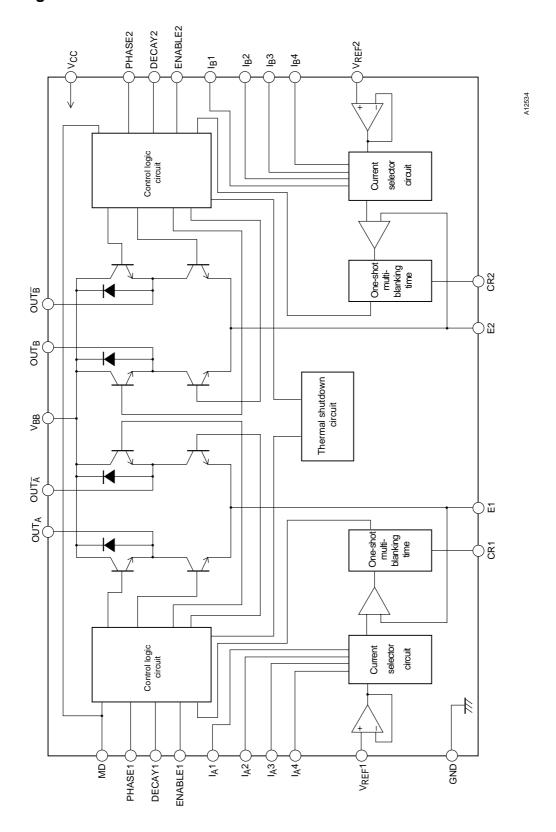
Pin Function

Pin number	Pin name	Function description					
1	MD	Sets the OFF time for FAST mode and SLOW mode in MIX DECAY					
'	WID	Setting input range: 4V to 1.5V					
2	V _{REF} 1	Output set current reference supply pins					
13	V _{REF} 2	Setting voltage range: 0V to 3V					
3	CR1	Output OFF time setting pins for switching operation					
12	CR2	Output Of 1 time setting pine for switching operation					
4	E1	Pins for controlling the set current with sensing resistor RE					
11	E2	First of controlling the set current with sensing resistor ICE					
5	DECAY1	SLOW mode/FAST mode selector pins					
10	DECAY2	SLOW DECAY: H					
		FAST DECAY: L					
6	$OUT_{\bar{A}}$						
7	OUTA	Output pins					
8	OUTĒ	Cathat billio					
9	OUTB						
14	V_{BB}	Output stage supply voltage pin					
15	GND	Ground pin					
27	PHASE1	Output phase selector input pins					
16	PHASE2	Output phase selector input phis					
26	ENABLE1	Output ON/OFF setting input pins					
17	ENABLE2	Output Of 4/Of 1 Setting Input pins					
22, 23	I _A 4, I _A 3						
24, 25	I _A 2, I _A 1	Output set current digital input pins					
21, 20	I_B4 , I_B3	15-stage voltage setting					
19, 18	I _B 2, I _B 1						
28	V _{CC}	Logic block supply voltage pin					



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Block Diagram

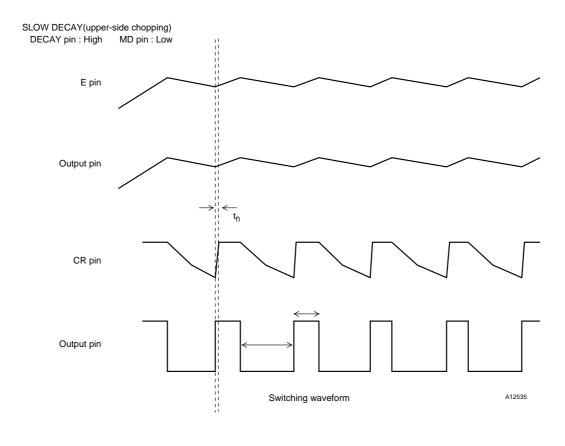


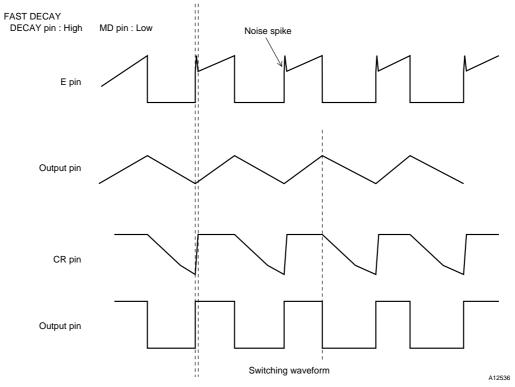
Sequence Table

	Ė			Pha	ıse A						Pha	ise B			Phase 1-2	DI 144.0	DI 014/4 0	DI (11/4 0
No.	I _A 4	I _A 3	I _A 2	I _A 1	ENA1	PHA1	I _{OUT}	I _B 4	I _B 3	I _B 2	I _B 1	ENA2	PHA2	l _{OUT}	Pliase 1-2	Phase W1-2	Phase 2W1-2	Phase 4W1-2
0	1	1	1	1	0	0	100%	0	0	1	0	1	*	0%	V	√	√	√
1	1	1	1	1	0	0	100	0	0	1	0	0	0	17.39				√
2	1	1	1	1	0	0	100	0	0	1	1	0	0	26.08			√	√
3	1	1	1	0	0	0	96.65	0	1	0	0	0	0	34.78				√
4	1	1	0	1	0	0	91.30	0	1	0	1	0	0	43.48		√	√	√
5	1	1	0	0	0	0	86.95	0	1	1	0	0	0	52.17				√
6	1	0	1	1	0	0	82.61	0	1	1	1	0	0	60.87			√	√
7	1	0	1	0	0	0	78.26	1	0	0	0	0	0	69.56				√
8	1	0	0	1	0	0	73.91	1	0	0	1	0	0	73.91	√	√	√	√
9	1	0	0	0	0	0	69.56	1	0	1	0	0	0	78.26				√
10	0	1	1	1	0	0	60.87	1	0	1	1	0	0	82.61			√	√
11	0	1	1	0	0	0	52.17	1	1	0	0	0	0	86.95				√
12	0	1	0	1	0	0	43.48	1	1	0	1	0	0	91.30		√	√	√
13	0	1	0	0	0	0	34.78	1	1	1	0	0	0	96.65				√
14	0	0	1	1	0	0	26.08	1	1	1	1	0	0	100			√	√
15	0	0	1	0	0	0	17.39	1	1	1	1	0	0	100				√
16	0	0	0	1	1	*	0	1	1	1	1	0	0	100	√	√	√	√
17	0	0	1	0	0	1	17.39	1	1	1	1	0	0	100				√
18	0	0	1	1	0	1	26.08	1	1	1	1	0	0	100			√	√
19	0	1	0	0	0	1	34.78	1	1	1	0	0	0	95.65				√
20	0	1	0	1	0	1	43.48	1	1	0	1	0	0	91.30		√	√	√
21	0	1	1	0	0	1	52.17	1	1	0	0	0	0	86.95				√
22	0	1	1	1	0	1	60.87	1	0	1	1	0	0	82.61			√	√
23	1	0	0	0	0	1	69.56	1	0	1	0	0	0	78.26				√
24	1	0	0	1	0	1	73.91	1	0	0	1	0	0	73.91	√	√	√	√
25	1	0	1	0	0	1	78.26	1	0	0	0	0	0	69.56				√
26	1	0	1	1	0	1	82.61	0	1	1	1	0	0	60.87			√	√
27	1	1	0	0	0	1	86.95	0	1	1	0	0	0	52.17				√
28	1	1	0	1	0	1	91.30	0	1	0	1	0	0	43.48		V	√	√
29	1	1	1	0	0	1	95.65	0	1	0	0	0	0	34.78				√
30	1	1	1	1	0	1	100	0	0	1	1	0	0	26.08			√	√
31	1	1	1	1	0	1	100	0	0	1	0	0	0	17.39				√

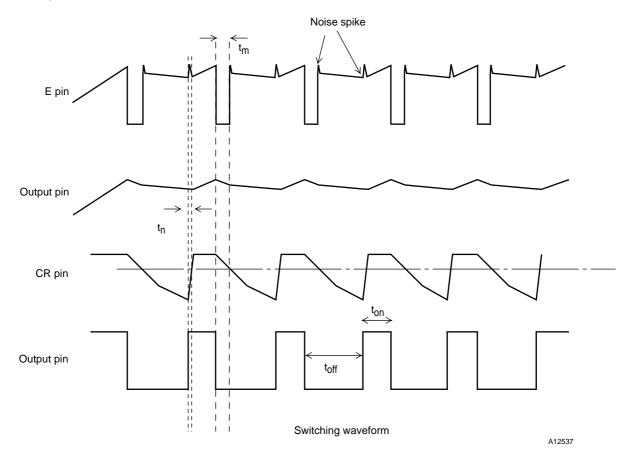
^{* :} lout percentage (%) is the calculated setting value.

Switch Timing Chart during PWM Drive





MIX DECAY



 t_{on} : Output ON time t_{off} : Output OFF time

 $t_{\rm m}^{\rm -}$: FAST DECAY time in MIX DECAY mode

 t_{n} : Noise cancelling time

MIX DECAY logic setting

DECAY pin: L

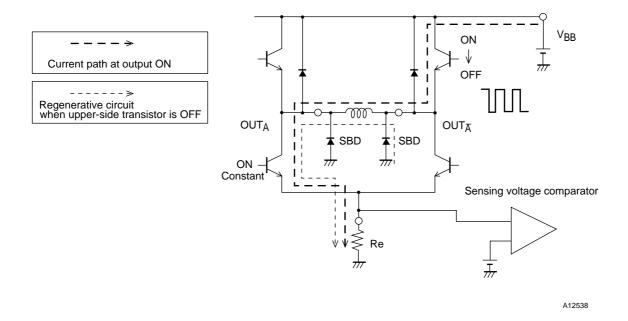
MD pin : 1.5V to 4.0V voltage setting

CR voltage and MD pin voltage are compared to select dual-side chopping or upper-side chopping.

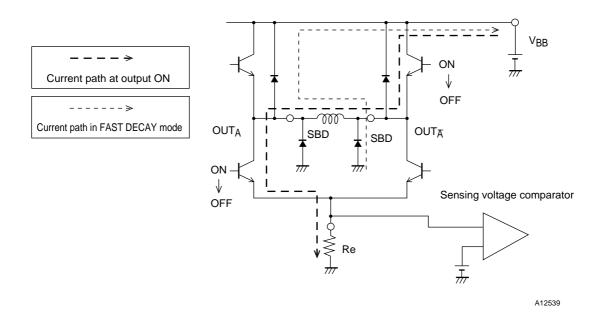
CR voltage > MD pin voltage: dual-side chopping CR voltage < MD pin voltage: top-side choppinng

SLOW DECAY current path

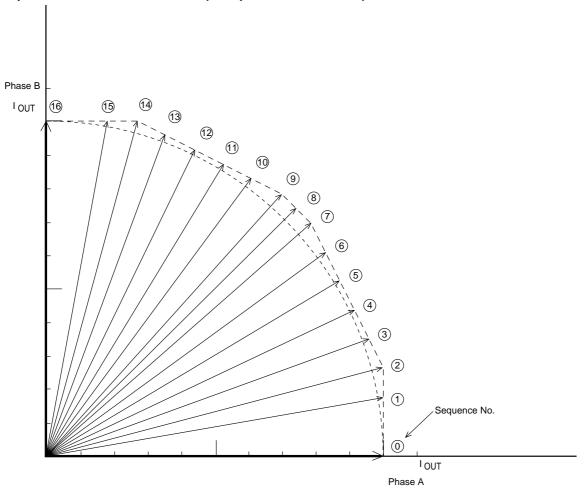
Regenerative current during upper-side transistor switching operation



Current path in FAST DECAY mode



Composite Vectors of Set Current (1 step normalized to 90°)

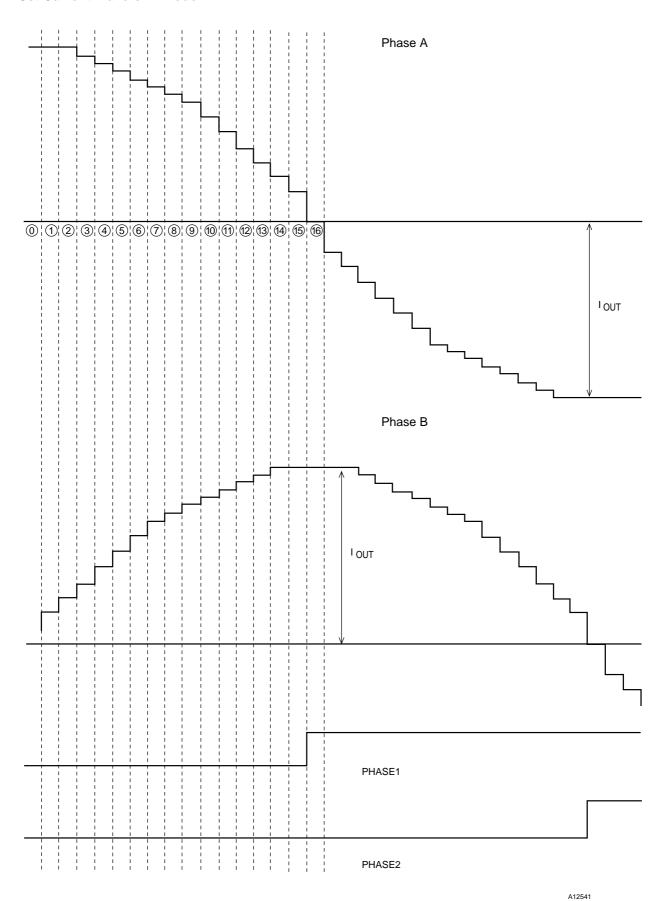


No.	θ	Rotation angles	Composite vectors
0	θ0	0°	100.0
1	θ1	9.87°	101.5
2	θ2	14.6°	103.35
3	θ3	20.0°	101.78
4	θ4	25.5°	101.12
5	θ5	30.96°	101.4
6	θ6	36.38°	102.61
7	θ7	41.63°	104.7
8	θ8	45.0°	104.5
9	θ9	48.37°	104.7
10	θ10	53.62°	102.61
11	θ11	59.04°	101.4
12	θ12	64.5°	101.12
13	θ13	70.0°	101.78
14	θ14	75.4°	103.35
15	θ15	80.13°	101.5
16	θ16	90.0°	100.0

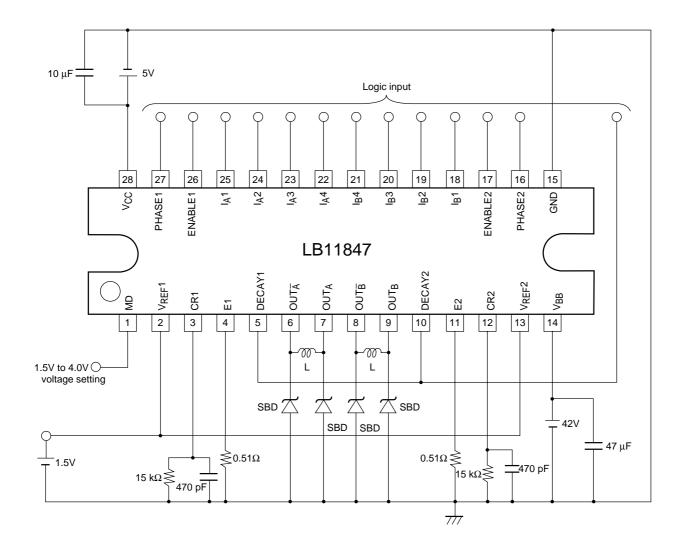
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^{*} Rotation angle and composite spectrum are calculated values.

Set Current Waveform Model



Sample Application Circuit



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Notes on Usage

1. External diodes

Because this IC uses upper-side transistor switching in SLOW DECAY mode and dual-side transistor switching in FAST DECAY mode, it requires external diodes between the OUT pins and ground for the regenerative current during switching OFF. Use Schottky barrier diodes with low VF.

2. V_{REF} pin

Because the V_{REF} pin serves for input of the set current reference voltage, precautions against noise must be taken. The input voltage range is 0 to 3.0V.

3. GND pin

The ground circuit for this IC must be designed so as to allow for high-current switching. Blocks where high current flows must use low-impedance patterns and must be removed from small-signal lines. Especially the ground connection for the sensing resistor RE at pin E, and the ground connection for the Schottky barrier diodes should be in close proximity to the IC ground.

The capacitors between V_{CC} and ground, and V_{BB} and ground should be placed close to the V_{CC} and V_{BB} pins, respectively.

4. Simultaneous ON prevention function

This IC incorporates a circuit to prevent feedthrough current when phase switching. For reference, the output ON and OFF delay times at PHASE and ENABLE switching are given below.

Reference data * typical value

		Sink side	Source side
PHASE switching	ON delay time	1.9 μs	2.2 μs
(Low -> High)	OFF delay time	0.8 μs	1.8 µs
PHASE switching	ON delay time	1.4 μs	1.7 µs
(High -> Low)	OFF delay time	0.9 μs	1.35 µs
ENABLE switching	ON delay time	2.15 μs	2.75 μs
	OFF delay time	1.2 μs	5.8 μs

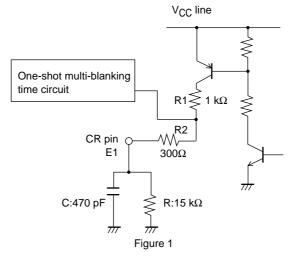
5. Noise canceler

This IC has a noise canceling function to prevent malfunction due to noise spikes generated when switching ON. The noise cancel time t_n is determined by internal resistance of the CR pin and the constant of the externally connected CR components. The constant also determines the switching OFF time.

Figure 1 shows the internal configuration at the CR pin, and Figure 2 shows the CR pin constant setting range.

*The CR constant setting range in Figure 2 on page 15 is given for reference. It applies to a switching OFF time in the range from 8 to 100 μ s. The switching time can also be made higher than 100 μ s. However, a capacitor value of more than several thousand pF will result in longer noise canceling time, which can cause the output current to become higher than the set current. The longer switching OFF time results in higher output current ripple, causing a drop in average current and rotation efficiency. When keeping the switching OFF time within 100 μ s, it is recommended to stay within the CR constant range shown in Figure 2.

Internal configuration at CR pin



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Switching OFF Time and CR Setting Range

(t_{off} time : approx. 8 to 100 $\mu\text{s})$

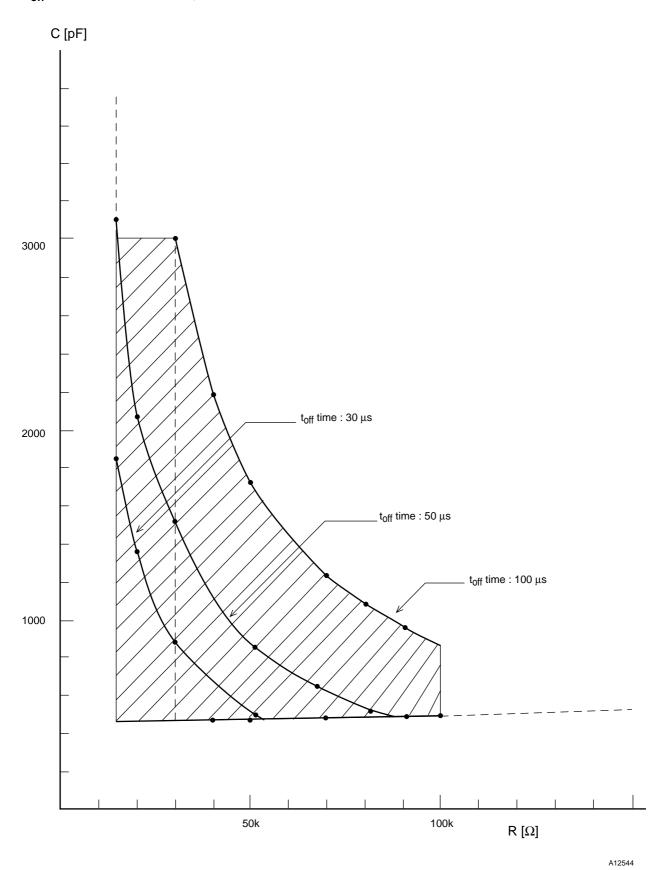


Figure 2

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