

LB1673M

3-Phase Brushless, Sensorless Motor Driver

Applications

Rotational control of brushless motors for use in audio applications such as headphone stereos, micro-cassette recorders, mini-cassette recorders.

Function and Features

- Brushless, sonsorless motor drive (3-phase half-wave drive).
- Bidirectional motor drive.
- On-chip speed control function (V servo type).
- On-chip reference votlage.
- On-chip one comparator (PNP input, NPN open collector output).

Package Dimensions

unit:mm



Specifications

Absolute Maximum Ratings at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage V _{CC} max			5	V
Output Transistor Breakdown votlage	V _{SUS} max		10	V
Output current	IM		1	А
Allowable power dissiaption	Pd max		0.58	W
Operating temperature	Topr		0 to +80	°C
Storage temperature	Tstg		-40 to +125	°C

Allowable Operating Conditions at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	VCC		1.0 to 3.5	V

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Electrical Characteristics at Ta = 25°C

Decemeter	Symbol	Conditions	Ratings			Linit
Parameter			min	typ	max	
Supply current 1	I _{CC} (L)	START pin low		0	10	mA
Supply current 2	ICC(H)	START pin high		4.8	10	μA
Reference votlage	Vref		0.49	0.52	0.55	V
Voltage characteristic of reference voltage	$\frac{\Delta Vref}{Vref/\Delta VCC}$	$V_{CC}=1$ to 3.5V		0.3	1.0	%/V
Load characterisric of reference voltage	<u>∆Vref</u> ∆Iref	Iref=0 to -60µA		-0.03		mV/μA
Temperature characteristic of reference voltage	$\frac{\Delta \text{Vref}}{\text{Vref}} / \Delta \text{Ta}$	Ta=0 to +80°C		0		%/°C
Speed signal detection accuracy	Vsp	V _{IN} =500mV	135	145	155	mV
Speed signal correlation error			-5		5	%
Voltage characteristic of speed signal	$\frac{\Delta V sp}{V sp} / \Delta V CC$	$V_{CC}=1$ to 3.5V		0.2	1.0	%/V
Temperature characteristic of speed signal	<u>∆Vsp</u> /∆Ta Vsp	Ta=0 to +60°C		0		%/°C
Current detection accuracy	V _{RI}	V _{IN1} =0.3V, V _{IN2} =1V	50	65	80	mV
Current detection ratio	КI	V _{IN2} =1 to 1.3V	0.14	0.17	0.25	
Pin OSC flow-out current	losc	Measured as pin OSC is 0.4V	2.6	3.8	5.0	μA
Starting pulse width	TOSC	C _S =0.47µF		60		ms
COM pull-in current	V _{COM} Θ	Short V _{CC} with COM	20	30	40	μA
Output saturation votlage	Vsat	V _{CC} =1V, I _m =0.2A		0.09	0.25	V
Logic input high-level voltage	V _H		0.9			V
Logic input low-level votlage	VL				0.3	V
Comparator offset votlage	VOFF		-10		+10	mV
Comparator output current	IOFF	V _{CC} =1V, OUT1=V _{CC}	100			μA

Equivalent Circuit Block Diagram





Pin Assignment



If the capacitance of the capacitor in the output section is large and the capacitance of C_S is small, the starting votlage may rise at low temperatures. In 3V-use, reverse rotation of a motor would not be well, consider the resistance of Rcom.

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(JIDO (LOGIC)

Top view

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Pin Description

Unit (resistance : Ω, capacitance : F)

VR 30k

Pin No.	Pin name	Description
1	GND	GND pin for the whole circuit.
2	V	V phase output pin
3	PW	W phase output drive transistor base
4	DW	W phase output transistor base
5	W	W phase output pin
6	DR	Pin for selecting the direction of rotation (H : forward)
7	Vref	Reference voltage (0.5V)
8	START	High active
9	Vsp	Speed signal (induced voltage) detection
10	IN⊕	Speed signal error amp reference input
11	OUT	Speed signal error amp output. The motor current is fed back.
12	GND	GND pin for logic circuiit.
13	RI	Pin for detecting the motor current
14	IN1	Oinput of internal comparator (PNP base input)
15	IN2	\oplus input of internal comparator (PNP base input)
16	OUT1	Output of internal comparator (NPN open collector)
17	OSC	Pin for setting the starting pulse width
18	COMΘ	Pin for providing a supplementary function for the current control circuit at the time of start or selection of direction of rotation
19	V _{CC}	Power supply pin
20	PU	U phase output drive transistor base
21	DU	U phase output transistor base
22	U	U phase output pin
23	PV	V phase output drive transisitor base
24	DV	V phase output transistor base

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