



# **Dual Bidirectional Motor Driver**

#### Overview

The LB1644 is a dual bidirectional motor driver. Since each channel has a 2-input logic circuit and performs bidirectional driving and braking functions, it is capable of direct driving 2pcs. of motor of various types rated at 6 to 24V. The output voltage can be varied by using external zener diodes.

It is especially suited for dual motor drive (reel motor, loading motor, cassette motor in VCR) and for stepping motor drive.

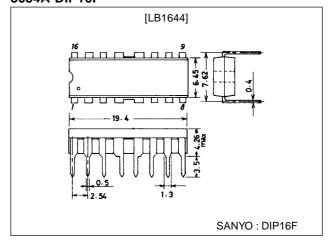
#### **Features**

- With power transistors for motor drive contained, capable of withstanding dash current of 1A max.
- Performs braking function at the motor stop mode.
- Contains elements to absorb motor dash current.
- Input interfaceable to MOS LSI.
- Minimum number of external parts required.
- Wide operating voltage range.
- Contains thermal shutdown protector.

# **Package Dimensions**

unit:mm

#### 3054A-DIP16F



# **Specifications**

### Absolute Maximum Ratings at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage	V <sub>CC</sub> max		25	V
Input voltage	VIN		25	V
Output current	lout		±1	А
Allowable power dissipation	Pd max		1.44	W
Operating temperature	Topr		-25 to +65	°C
Storage temperature	Tstg		-55 to +125	°C

#### Allowable Operating Conditions at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	VCC		7 to +25	V

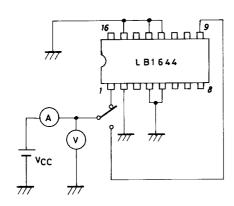
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### Electrical Characteristics at Ta = 25°C

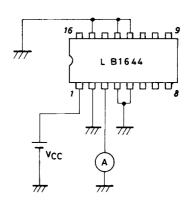
Parameter	Symbol	Conditions	Ratings			Unit	
Farameter	Syllibol	Conditions	min	typ	max	Uill	
Current drain	I <sub>CC</sub> 1	Pin1, Braking mode, R <sub>L</sub> =∞		8.0	11.5	mA	
	I <sub>CC</sub> 2	Pin9, Braking mode, R <sub>L</sub> =∞		7.0	10.0	mA	
Output leakage current	lOL	Braking mode, R <sub>L</sub> =∞ per output pin		40	120	μA	
Input threshold voltage	V <sub>th</sub>	R <sub>L</sub> =∞	0.9	1.05	1.20	V	
Output voltage	VO	R <sub>L</sub> =60Ω, V <sub>Z</sub> =7.4V	6.5	7.2	7.5	V	
Output tr saturation voltage (upper)	\/ 1	I <sub>OUT</sub> =300mA		1.9	2.3	V	
	V <sub>sat</sub> 1	I <sub>OUT</sub> =500mA		2.0	2.4	V	
Output tr saturation voltage (lower)	\/ 2	I <sub>OUT</sub> =300mA		0.3	0.55	V	
	V <sub>sat</sub> 2	I <sub>OUT</sub> =500mA		0.5	0.7	V	

### **Test Circuits (per channel)**

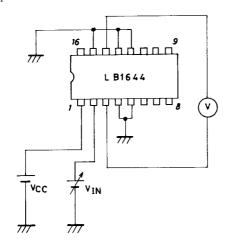
(1) ICC1 (1pin) ICC2 (9pin)

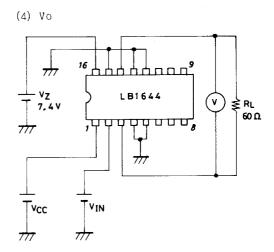


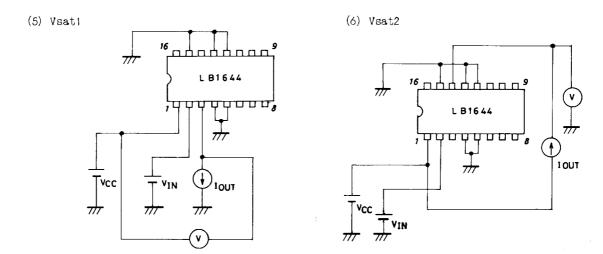




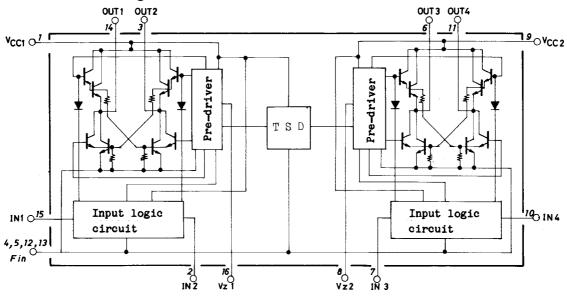
(3) Vth







### **Equivalent Circuit Block Diagram**



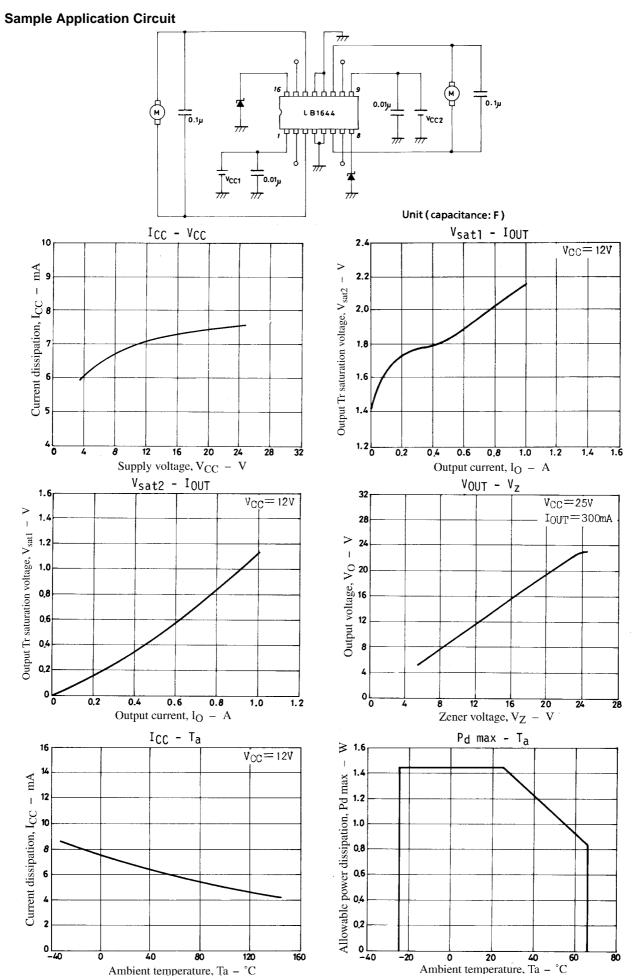
## **Truth Table of Logic Circuit**

IN1	IN2	OUT1	OUT2	IN3	IN4	OUT3	OUT4
0	0	L	L	0	0	L	L
1	0	Н	L	1	0	Н	L
0	1	L	Н	0	1	L	Н
1	1	L	L	1	1	L	L

Note : A capacitor of  $0.01 \mu F$  or greater must be connected across  $V_{\mbox{\footnotesize{CC}}}1,\,2$  and GND.

	INPUT			OUT	PUT		MODE		
IN1	IN2, 3	IN4	OUT1	OUT2	OUT3	OUT4	M1	M2	
0	0	0	L	L	L	L	Braking	Braking	
1	0	0	Н	L	L	L	Forward/reverse	Braking	
0	1	1	L	Н	L	L	Reverse/forward	Braking	
1	1	0	L	L	Н	L	Braking	Forward/reverse	
0	0	1	L	L	L	Н	Braking	Reverse/forward	
1	1	1	L	Ĺ	Ĺ	Ĺ	Braking	Braking	

The remaining input states 1, 0, 1 and 0, 1, 0 are not inhibited.



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