# 2-phase half-wave motor predriver BA6402F

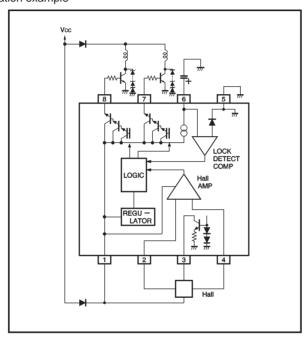
The BA6402F is a 2-phase, half-wave motor predriver suitable for fan motors.

#### Features

- Lock detection and rotational speed sensing mechanisms are built in.
- 2) Hall constant current source is built in.

 Compact 8-pin SOP package reduces the number of external components required.

Block diagram and application example



## ■Absolute maximum ratings (Ta = 25°C)

| Parameter             | Symbol | Limits          | Unit |
|-----------------------|--------|-----------------|------|
| Applied voltage       | Vcc    | 30              | V    |
| Power dissipation     | Pd     | 450*            | mW   |
| Operating temperature | Topr   | -20~+80         | Č    |
| Storage temperature   | Tstg   | <b>−55∼+125</b> | Ĉ    |
| Output current        | Іомах. | 70              | mA   |

<sup>\*</sup>Reduced by 4.5 mW for each increase in Ta of 1℃ over 25 ℃.

#### Recommended operating conditions

| Parameter       | Symbol | Min. | Тур. | Max.    | Unit | Conditions                                     |
|-----------------|--------|------|------|---------|------|--|
| Applied voltage | Vcc    | 4    | _    | 28      | ٧    | Operate within the allowable power dissipation |
| Input voltage   | Vвн    | 0.8  | _    | Vcc-0.2 | V    | for -20℃ < Ta < 80℃                            |

**Motor driver ICs BA6402F** 

| <ul> <li>Electrical characteristics</li> </ul> | (unless otherwise noted | , Ta = $25^{\circ}$ C and Vcc = $12V$ ) |
|--|-------------------------|---|
| The control of an action stills                |                         | , 1a - 25 0 and vcc - 12 v)             |

| Parameter                           | Symbol             | Min. | Тур. | Max. | Unit | Conditions |
|-------------------------------------|--------------------|------|------|------|------|------------|
| Supply current                      | lcc                | _    | 1.9  | 4.0  | mA   |            |
| Hall amplifier input hysteresis (十) | V <sub>hys</sub> + | 3    | _    | 15   | mV   |            |
| Hall amplifier input hysteresis (-) | V <sub>hys</sub> - | -3   | _    | -15  | mV   |            |
| Pin 3 constant current              | lз                 | 5    | 6.8  | 10   | mA   |            |
| Pin 6 constant current              | l6                 | 5    | 6.8  | 10   | μΑ   |            |
| Pin 6 clamp voltage                 | V <sub>6</sub>     | 3.1  | _    | 3.7  | V    |            |
| Pin 7 Output high level voltage     | V <sub>7</sub> H   | 10   | 10.5 | _    | V    | lo=10mA    |
| Pin 8 Output high level voltage     | V <sub>8H</sub>    | 10   | 10.5 | _    | V    | Io=10mA    |

# Rotational speed sensing and lock detection (6 pin)

The circuit around pin 6 is described in Fig. 1. Normally, the C6 external capacitor is charging or discharging around the Hall signal when the motor is running. When the motor is locked, discharging does not occur at C6 because the Hall signal stops switching. Charging continues at C6 until the voltage increases to the pin-6 clamp voltage, and then Q1 turns ON to turn OFF the output. With the pin-6 current being constant (I<sub>6</sub>=6.8µA, typical), the time required after the motor is locked until the output current is turned OFF (duration between B and C in Fig. 2) is determined by the C6 capacitance.

$$T_{\text{off}} = T_{\text{B-CE}} = \frac{\left(V_{\text{6CL}} - V_{\text{BEQ3}}\right) C_6}{I_6}$$

$$\stackrel{\leftarrow}{=} \frac{4V_{\text{BE}} \bullet C_6}{6.8 \mu A \text{ (Typ.)}}$$

$$\stackrel{\leftarrow}{=} 4.12 \times 10^5 \times C_6 \text{ (sec) (Typ.)}$$

where V<sub>6CL</sub> is pin-6 clamp voltage (nearly equal to 5V<sub>BE</sub>) For  $C_6=2.2\mu F$ , for example,  $T_{\text{off}}$  is about 0.91s (typical).

#### Operation notes

(1) Hall constant current source (3 pin, 6.8mA typically), which is directly connected with the IC bias circuit, is not available when pin 3 is OPEN (saturated).

## (2) Power dissipation

The allowable power dissipation is plotted against ambient temperature in Fig. 3.

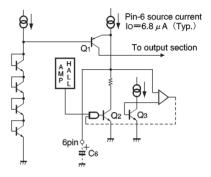


Fig.1

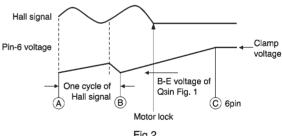


Fig.2

## Thermal derating curve

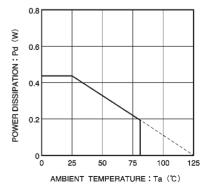


Fig.3

# (3) Power dissipation

The power consumed in the IC can be calculated from the following equation:

$$P_{C} = \sum_{n=1}^{3} P_{Cn}$$

1)  $P_{C1}$  is power consumed by the circuit current.  $P_{C1} = V_{CC} \times I_{CC}$ 

# 2) $P_{C2}$ is power consumed by the Hall current (pin 3). $P_{C2}=I_3\times V_3$

where V₃=pin 3 voltage. Connecting a resistor between the Vcc pin and pin 3 effectively reduces the IC current consumption.

#### Electrical characteristic curve

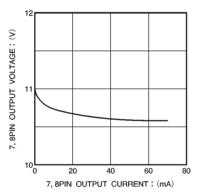
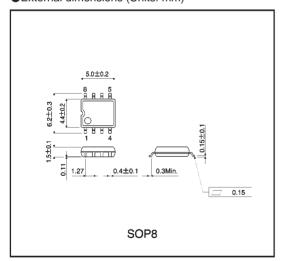


Fig.4 Output voltage vs. output current for pins 7 and 8

#### External dimensions (Units: mm)



3)  $P_{C3}$  is power consumed by the output current.

$$P$$
сз=( $V$ сс  $-V$ он)  $\times$  Iо

VoH is the HIGH level voltage of pins 7 and 8. Power consumption can be reduced by raising the hFE-rank of the external output transistor and thereby reducing the lo value. Make sure that your application does not exceed the allowable power dissipation of the IC.

#### (4) Restarting when motor is locked

The outputs are turned OFF if the motor is stopped for some reason. To restart the motor from this situation, turn off the power first, fully discharge the pin 6 capacitor next, and then turn on the power again.