

TOSHIBA BIPOLAR LINEAR INTEGRATED CIRCUIT SILICON MONOLITHIC

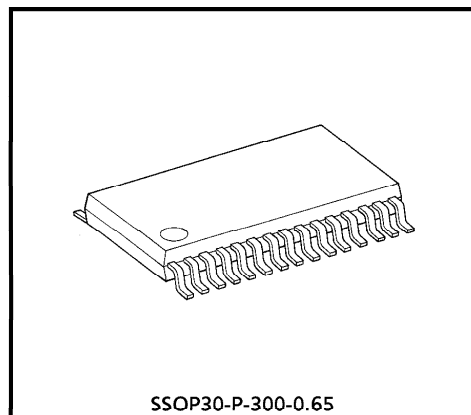
# TA8482FN

## BRIDGE DRIVER + SENSOR AMP 1-CHIP IC FOR DC MOTORS

TA8482FN is a loading motor driver for video camera. It is a 1-chip IC with tape top/end sensor amplifiers, reel FG amplifiers, and buffer amplifiers for servo error L.P.F.

### FEATURES

- 4 Modes : Forward Rotation, Reverse Rotation, Stop, and Brake
- Built-in Current Limiter
- Built-in Thermal Shutdown Circuit
- Built-in Tape Top/End Sensor Amplifiers
- 2 Built-in Reel FG Amplifiers
- 2 Built-in Buffer Amplifiers for Servo Error L.P.F.
- Built-in Buffer Limiter
- Package : VSOP-30

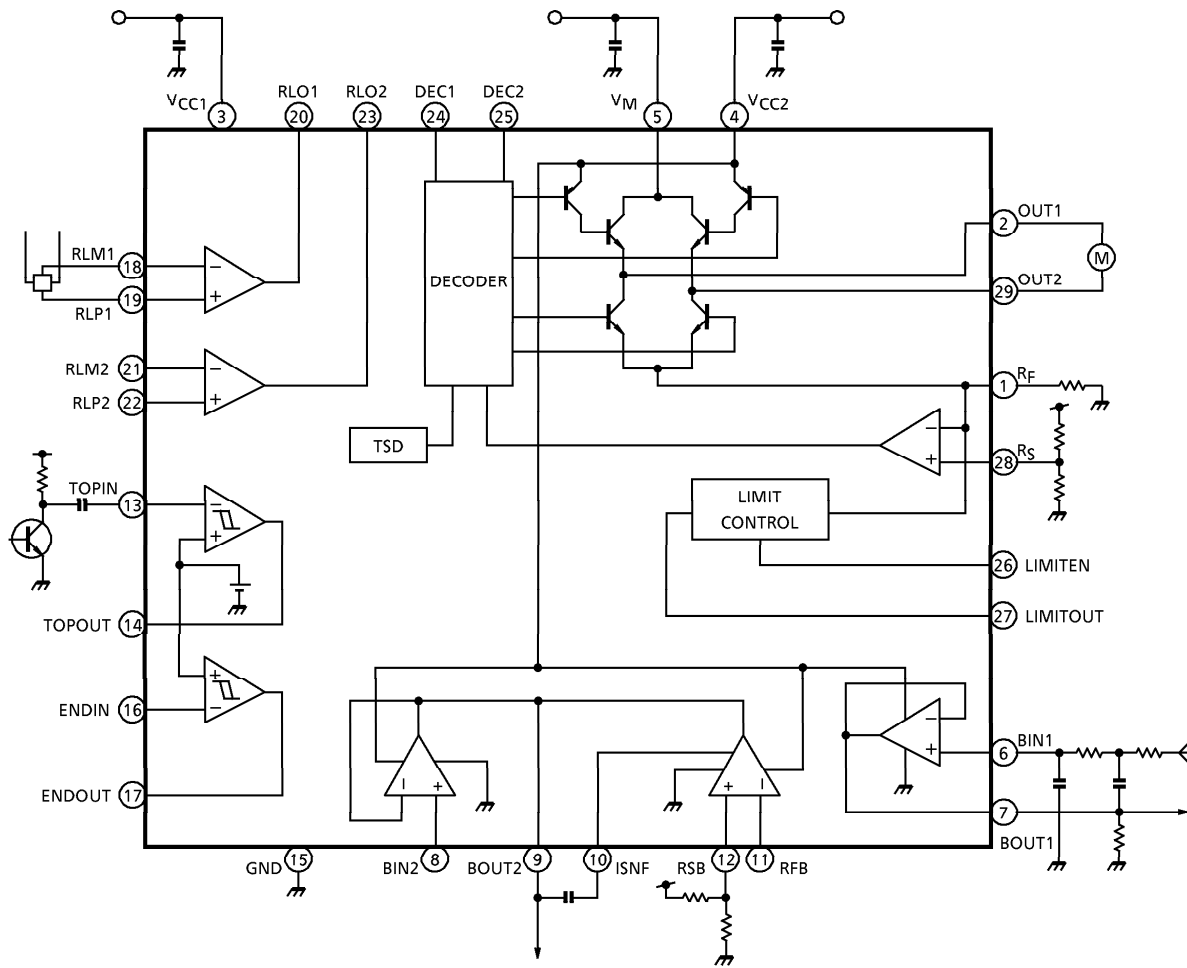


Weight : 0.17g (Typ.)

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## BLOCK DIAGRAM



## PIN FUNCTION

PIN No.	SYMBOL	PIN NAME
1	R <sub>F</sub>	Output current detect pin
2	OUT1	Motor drive output pin 1
3	V <sub>CC1</sub>	Power supply input pin 1
4	V <sub>CC2</sub>	Power supply input pin 2
5	V <sub>M</sub>	Motor drive voltage input pin
6	BIN1	Buffer amp 1 input pin
7	BOUT1	Buffer amp 1 output pin
8	BIN2	Buffer amp 2 input pin
9	BOUT2	Buffer amp 2 output pin
10	ISNF	Buffer limiter amp phase compensating pin
11	RFB	Buffer limiter amp input pin
12	RSB	Buffer limiter amp reference voltage input pin
13	TOPIN	Tape-top sensor amp input pin
14	TOPOUT	Tape-top sensor output pin
15	GND	GND pin
16	ENDIN	Tape-end sensor amp input pin
17	ENDOUT	Tape-end sensor amp output pin
18	RLM1	Reel FG amp 1 negative side input pin
19	RLP1	Reel FG amp 1 positive side input pin
20	RLO1	Reel FG amp 1 output pin
21	RLM2	Reel FG amp 2 negative side input pin
22	RLP2	Reel FG amp 2 positive side input pin
23	RLO2	Reel FG amp 2 output pin
24	DEC1	Decoder input pin 1
25	DEC2	Decoder input pin 2
26	LIMITEN	Limiter controller input pin
27	LIMITOUT	Limiter controller output pin
28	R <sub>S</sub>	Limiter amp reference voltage input pin
29	OUT2	Motor drive output pin 2
30	N.C	—

**TRUTH TABLE**  
DECODER CIRCUIT

DEC1	DEC2	OUT1	OUT2
L	L	Z	Z
H	L	H	L
L	H	L	H
H	H	L	L

Z : High impedance

**LIMITER CONTROLLER CIRCUIT**

LIMITEN	LIMITER AMP CIRCUIT	LIMITOUT
H	When operated (when output current is detected)	L
	When not operated	H
L	H	

**MAXIMUM RATINGS** (Ta = 25°C)

CHARACTERISTIC	SYMBOL	RATING	UNIT
Small Signal Section Supply Voltage	V <sub>CC1</sub>	10	V
Output Section Supply Voltage	V <sub>CC2</sub>	11	V
Output Section Supply Voltage	V <sub>M</sub>	8	V
Output Current	I <sub>O</sub>	0.6	A
Power Dissipation	P <sub>D</sub>	0.86 (Note 1)	W
		1.13 (Note 2)	
Operating Temperature	T <sub>opr</sub>	-20~80	°C
Storage Temperature	T <sub>stg</sub>	-55~150	°C

(Note 1) Single body

(Note 2) Substrate mounting (50×50×1.6mm Cu 40%)

(\*) Devices may break outside the range of maximum rating.

**OPERATING SUPPLY VOLTAGE RANGE** (Ta = 25°C)

CHARACTERISTIC	SYMBOL	OPERATING RANGE	UNIT
Small Signal Section Supply Voltage	V <sub>CC1</sub>	2.7~4.0	V
Output Section Supply Voltage	V <sub>CC2</sub>	V <sub>CC1</sub> ~9.0	V
Output Section Supply Voltage	V <sub>M</sub>	1.0~7.0 (Note 3)	V

(Note 3) V<sub>CC2</sub> ≥ V<sub>M</sub>

(\*) The range of operating conditions covers normal operations under the condition specified for electrical characteristics.

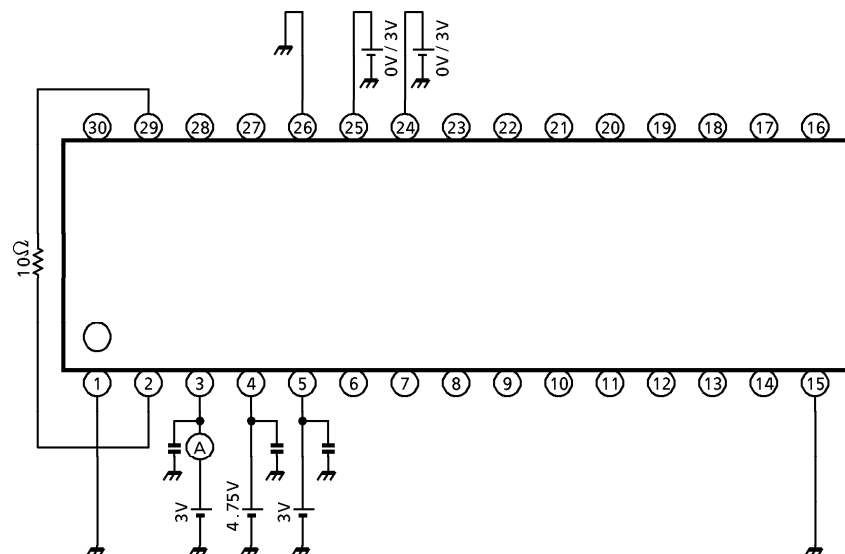
ELECTRICAL CHARACTERISTICS ( $V_{CC1} = 3.0V$ ,  $V_{CC2} = 4.75V$ ,  $V_M = 3.0V$ ,  $T_a = 25^\circ C$ )

CHARACTERISTIC			SYMBOL	TEST CIR- CUIT	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
Supply Current			$I_{CC11}$	1	$R_L = 10\Omega$ DEC1 : L, DEC2 : L	—	3	4.2	mA
			$I_{CC12}$		$R_L = 10\Omega$ DEC1 : H/L, DEC2 : L/H	—	20	30	
			$I_{CC13}$		$R_L = 10\Omega$ DEC1 : H, DEC2 : H	—	42	60	
			$I_{CC21}$	2	$R_L = 10\Omega$ , $V_{CC1} = 0V$ DEC1 : L, DEC2 : L	—	—	1	$\mu A$
			$I_{CC22}$		$R_L = 10\Omega$ DEC1 : L, DEC2 : L	—	0.7	1	mA
			$I_{CC23}$		$R_L = 10\Omega$ DEC1 : H/L, DEC2 : L/H	—	20	30	
			$I_{CC24}$		$R_L = 10\Omega$ DEC1 : H, DEC2 : H	—	0.7	1	
			$I_M$	3	$R_L = 10\Omega$ DEC1 : L, DEC2 : L	—	—	1	$\mu A$
Decoder Circuit	Input Voltage	"H" level	$V_{IN1}$	4	$R_L = 10\Omega$	2.0	—	—	V
		"L" level	$V_{IN2}$		$R_L = 10\Omega$	—	—	0.6	
	Input Current		$I_{IN}$		$V_{IN} = 3.0V$	—	—	3	$\mu A$
	Input Leakage Current		$I_{INL}$		$V_{IN} = 0V$	—	—	1	
Output Circuit	Saturation Voltage (Upper Side + Lower side)		$V_{sat} (H + L)$	5	$I_O = 0.2A$	—	0.3	0.45	V
					$I_O = 0.4A$	—	0.6	0.75	
Current Limiter Amp	Reference Voltage Input Range		$V_{RS}$	6		0.05	—	1.0	V
	Detecting Voltage		$V_{LIMIT}$	7	$R_L = 10\Omega$ , $R_F = 1\Omega$ $V_{RS} = 0.2V$	0.18	0.2	0.22	
Current Limiter Controller	Input Voltage	"H" level	$V_{LE} (H)$	8	$R_L = 10\Omega$	2.0	—	—	V
		"L" level	$V_{LE} (L)$		$R_L = 10\Omega$	—	—	0.6	
	Input Current		$I_{LC}$		$V_{LE} = 3.0V$	—	—	3	$\mu A$
	Input Leakage Current		$I_{LCL}$		$V_{LE} = 0V$	—	—	1	
	Output Voltage	"H" level	$V_{LO} (H)$		$I_O = 10\mu A$	$V_{CC1} - 0.5$	—	—	V
		"L" level	$V_{LO} (L)$		$I_O = 10\mu A$	—	—	0.4	

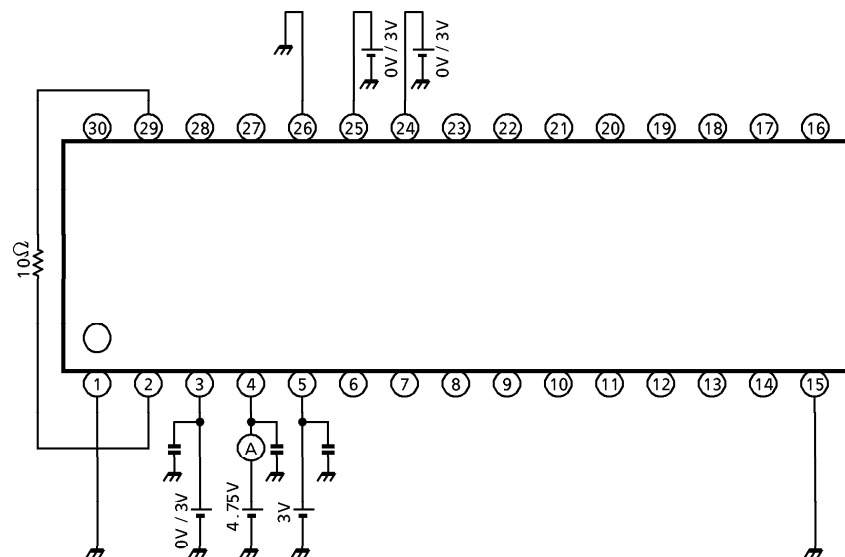
CHARACTERISTIC		SYMBOL	TEST CIR- CUIT	TEST CONDITIONS	MIN.	TYP.	MAX.	UNIT
Reel FG Amp	Common-Phase Voltage Range	V <sub>CMRFG</sub>	9		1.0	—	2.0	V
	Input Current	I <sub>FG</sub>	10	V <sub>CMRFG</sub> = 1.5V	—	—	1	μA
	Output Offset Voltage	V <sub>OFFG</sub>		—	0	± 290	mV	
	Closed Loop Voltage Gain	G <sub>VFG</sub>	11	f <sub>FG</sub> = 1kHz	27	29	31	dB
	Open Loop Voltage Gain	G <sub>VOFG</sub>	—	f <sub>FG</sub> = 1kHz Design assurance	—	55	—	dB
	Output Residual Voltage	V <sub>sat-FG</sub> (H)	12	I <sub>O</sub> = 10μA (Upper side)	—	—	0.2	V
V <sub>sat-FG</sub> (L)		I <sub>O</sub> = 10μA (Lower side)		—	—	0.2		
Top / End Sensor Amp	Input Resistance	R <sub>IN</sub>	13		4	5	6	kΩ
	Minimum Input Sensitivity	V <sub>HS</sub>	—	Design assurance	30	40	50	mV <sub>p-p</sub>
Buffer Amp	Input Voltage Range	V <sub>CMRBL</sub>	14		0	—	V <sub>CC2</sub>	V
	Input Current	I <sub>B</sub>		V <sub>BIN</sub> = 0V, (Note)	—	—	1	μA
	Input Offset Voltage	V <sub>OFB</sub>		V <sub>BIN</sub> = 1.5V	—	0	± 7	mV
	Output Voltage (Upper Side)	V <sub>OB</sub> (H)	15	R <sub>L</sub> = 20kΩ (against GND)	V <sub>CC2</sub> – 1.7	—	—	V
	Output Voltage (Lower Side)	V <sub>OB</sub> (L)		V <sub>BOUT</sub> = 0V, R <sub>L</sub> = 500kΩ (against V <sub>CC2</sub> )	—	—	0.1	V
	Band Width	f <sub>B</sub>	—	Design assurance	—	800	—	kHz
Buffer Limiter Amp	Common-Phase Input Voltage Range	V <sub>CMRBL</sub>	16		0	—	V <sub>CC2</sub> – 1.7	V
	Input Current	I <sub>BL</sub>	17	V <sub>BL</sub> = 0V	—	—	1	μA
	Input Offset Voltage	V <sub>OFBL</sub>	18	V <sub>RSB</sub> = 1.5V	—	0	± 7	mV
Thermal Shutdown Circuit Operating Temperature		T <sub>SD</sub>	—	Design assurance	—	150	—	°C

(Note) Design target value is fixed at  $0.5\mu A$  (Max.)

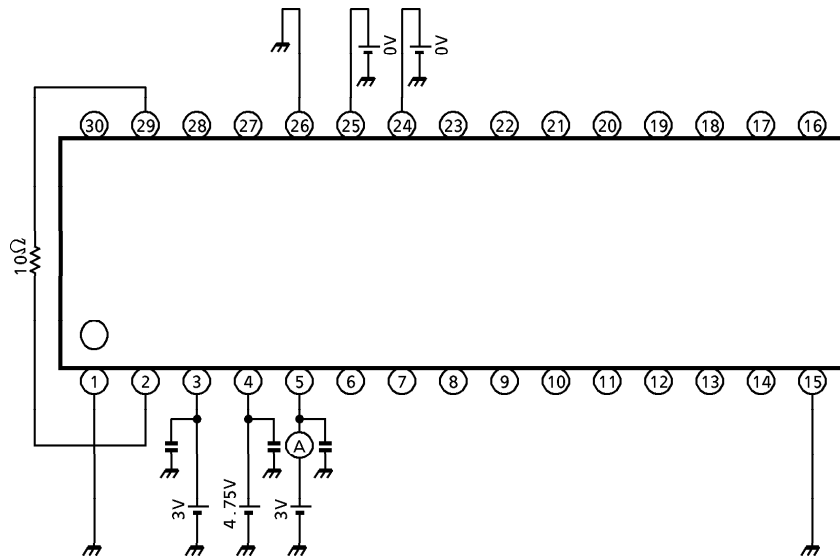
## TEST CIRCUIT

1.  $I_{CC1}$ ,  $I_{CC2}$ ,  $I_{CC3}$ 

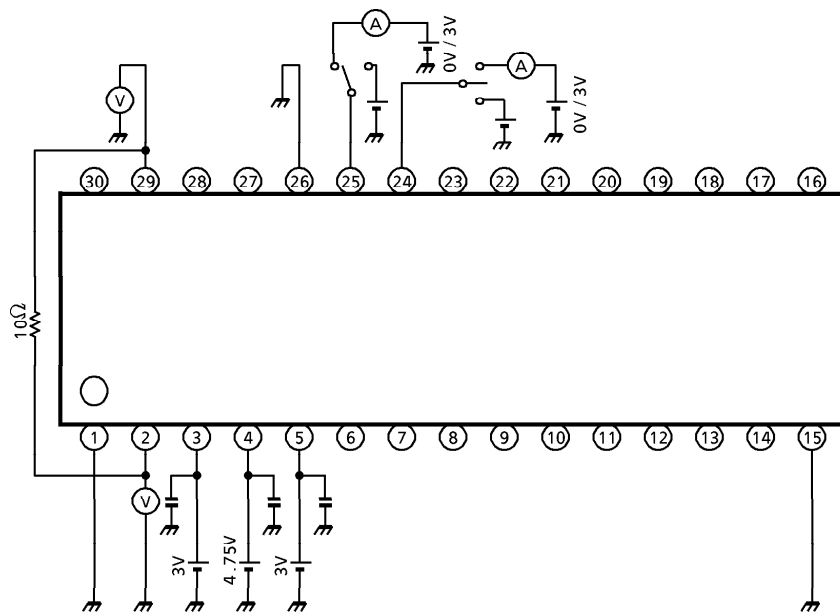
- $I_{CC11}$   
DEC1 = L, DEC2 = L
- $I_{CC12}$   
DEC1 = H, DEC2 = L  
and  
DEC1 = L, DEC2 = H
- $I_{CC13}$   
DEC1 = H, DEC2 = H

2.  $I_{CC21}$ ,  $I_{CC22}$ ,  $I_{CC23}$ ,  $I_{CC24}$ 

- $I_{CC21}$   
 $V_{CC1} = 0V$ , DEC1 = L, DEC2 = L
- $I_{CC22}$   
 $V_{CC1} = 3V$ , DEC1 = L, DEC2 = L
- $I_{CC23}$   
DEC1 = H, DEC2 = L  
and  
DEC1 = L, DEC2 = H
- $I_{CC24}$   
DEC1 = H, DEC2 = H

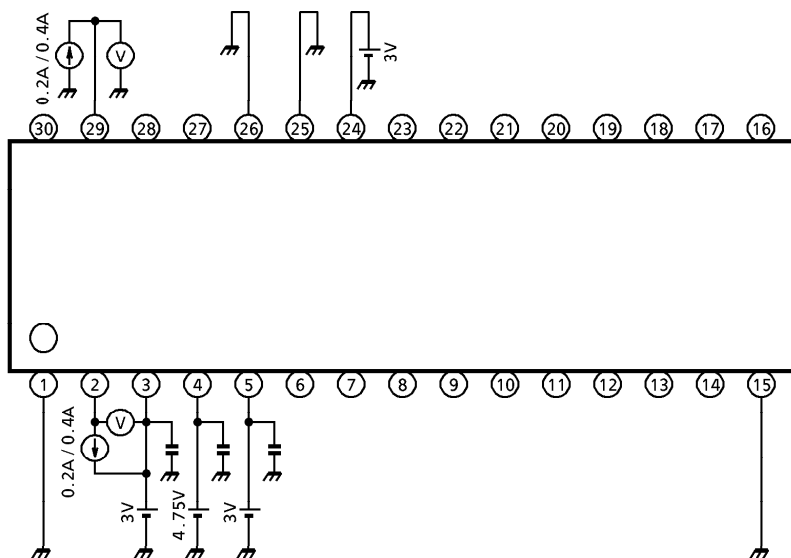
3.  $I_M$ 

- $I_M$   
DEC1 = L, DEC2 = L

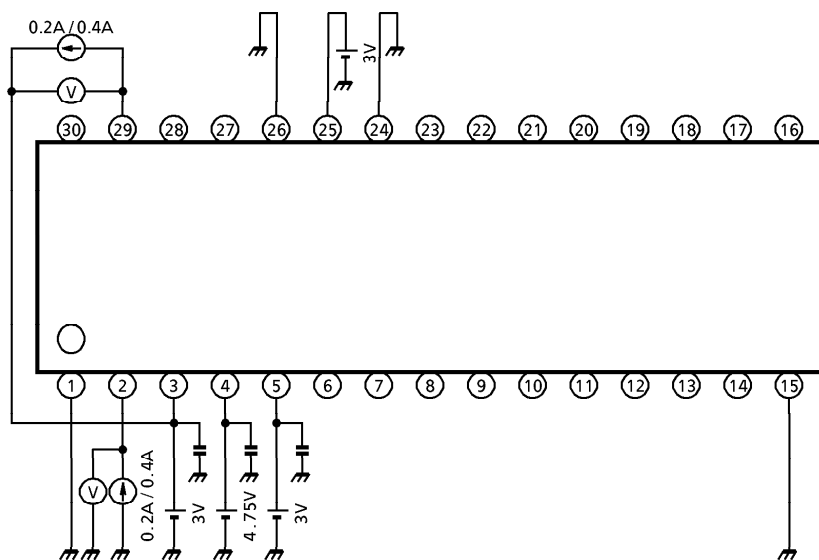
4.  $V_{IN1}$ ,  $V_{IN2}$ ,  $I_{IN1}$ ,  $I_{INL}$ 

- $V_{IN1}$ ,  $V_{IN2}$   
 $V_{DEC1} = 0.6V$ ,  $V_{DEC2} = 2.0V$   
 $V_{DEC1} = 2.0V$ ,  $V_{DEC2} = 0.6V$   
 $V_{DEC1} = 2.0V$ ,  $V_{DEC2} = 2.0V$   
 Check the output functions on the above-mentioned three conditions.
- $I_{IN1}$   
 $V_{IN} = 3.0V$
- $I_{INL}$   
 $V_{IN} = 0V$



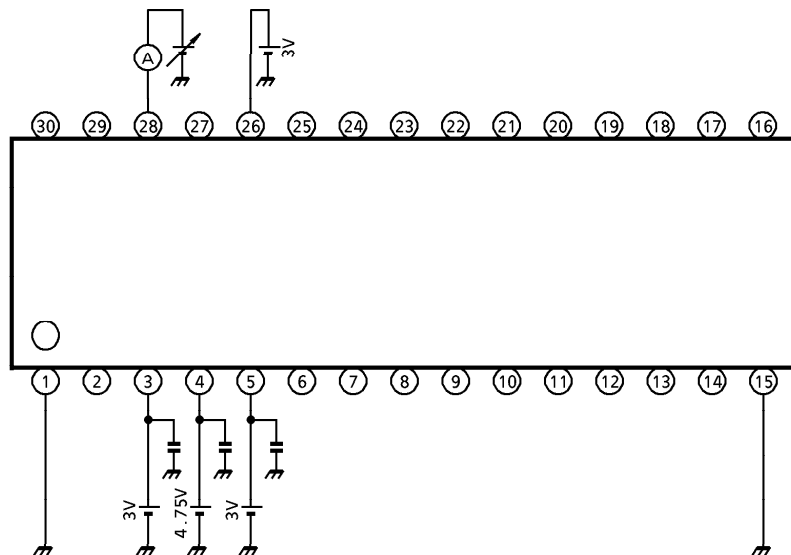
5.  $V_{\text{sat}} (H + L)$ 

- $V_{\text{sat}} (H + L)$   
Input DEC1 = H, DEC2 = L, and measure OUT1 (upper side) and OUT2 (lower side) with regard to  $I_O = 0.2A / 0.4A$ .

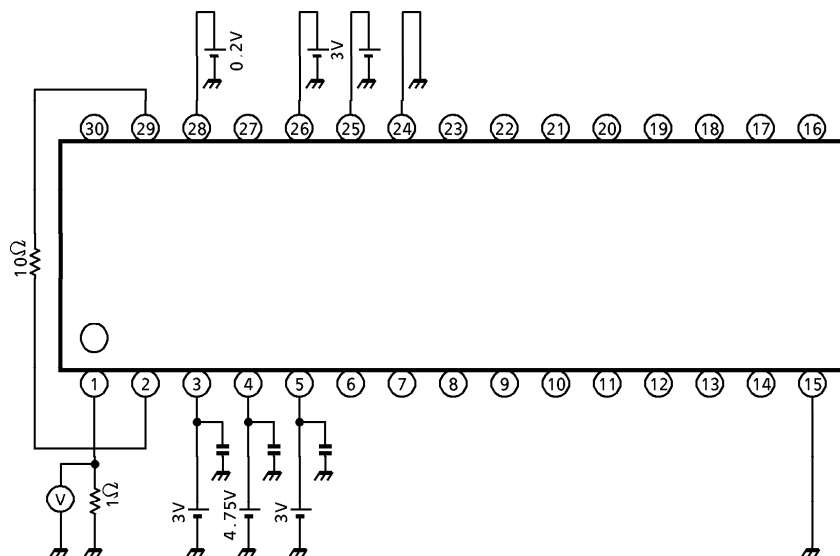


- $V_{\text{sat}} (H + L)$   
Input DEC1 = H, DEC2 = L, and measure OUT1 (upper side) and OUT2 (lower side) with regard to  $I_O = 0.2A / 0.4A$ .

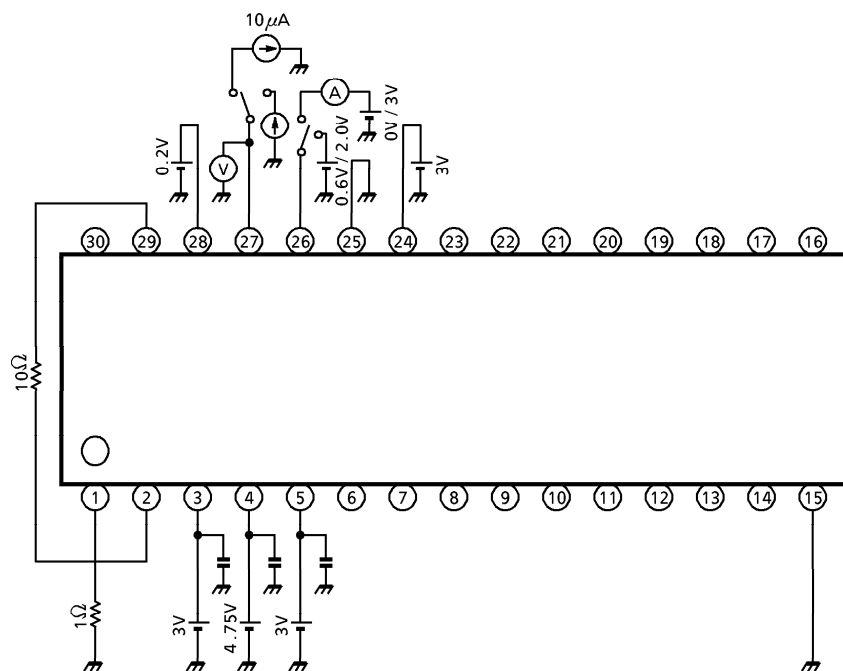
The sum of the upper/lower values of OUT1 and OUT2 is fixed at  $V_{\text{sat}} (H + L)$ .

6.  $V_{RS}$ 

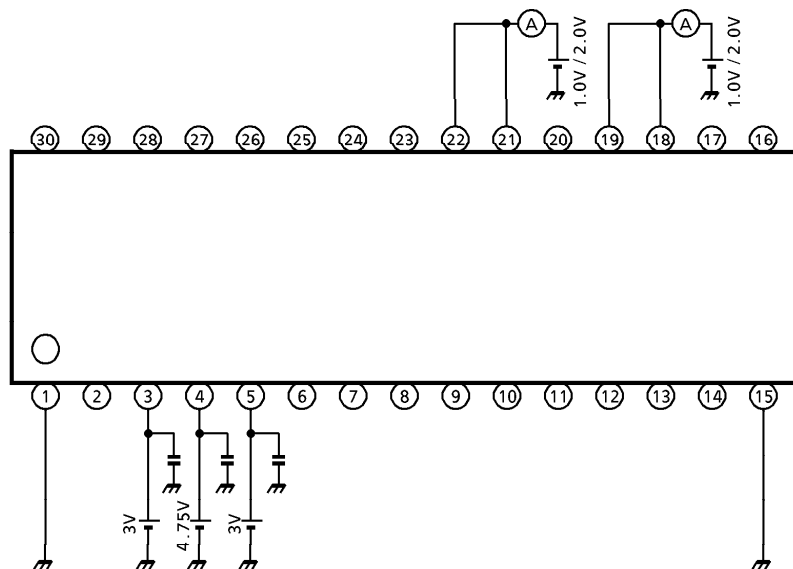
- $V_{RS}$   
Change  $V_{RS}$  and measure input current.

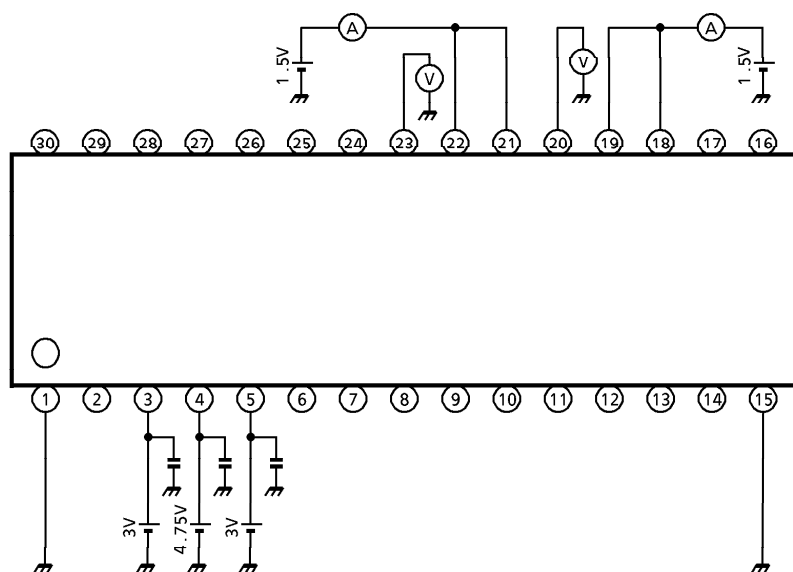
7.  $V_{LIMIT}$ 

- $V_{LIMIT}$   
Input  $V_{RS} = 0.2V$  and measure  $R_F (= 1\Omega)$  generating voltage at the time of limiter amp operation.

8.  $V_{LE}(H)$ ,  $V_{LE}(L)$ ,  $I_{LC}$ ,  $I_{LCL}$ ,  $V_{LO}(H)$ ,  $V_{LO}(L)$ 

- $V_{LE}(H)$ ,  $V_{LE}(L)$   
Input  $V_{LE} = 2.0V / 0.6V$  in a limiter amp operating state and check the LIMIT OUT terminal voltage.
- $I_{LC}$   
 $V_{LE} = 3.0V$
- $I_{LCL}$   
 $V_{LE} = 0V$
- $V_{LO}(H)$ ,  $V_{LO}(L)$   
Input  $V_{LE} = 0.6V / 2.0V$  in a limiter amp operating state and measure the LIMIT OUT terminal voltage when  $I_O = 10\mu A$ .

9.  $V_{CMRFG}$ 

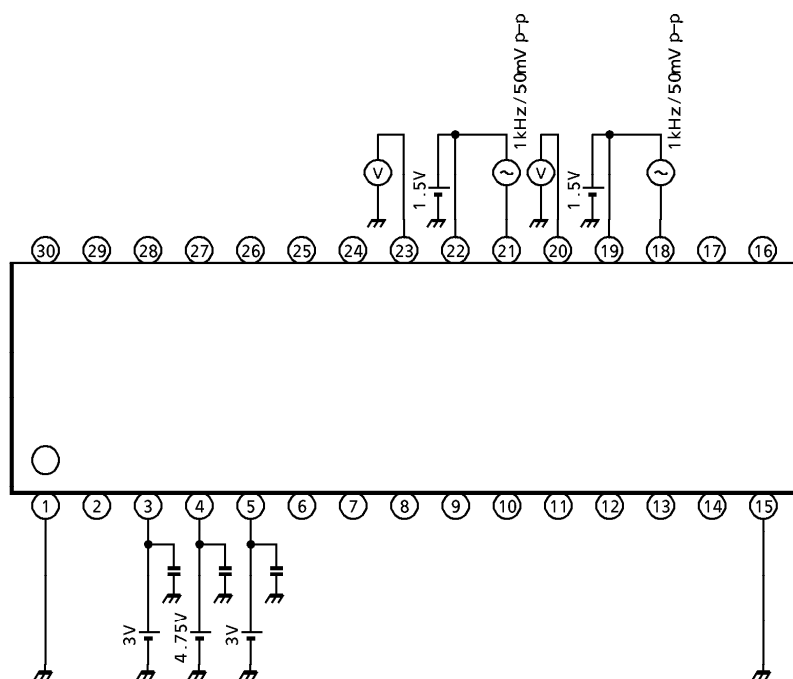
10.  $I_{FG}$ ,  $V_{OFFG}$ 

- $I_{FG}$   
Measure the input current ( $I_{FG}'$ ) when  $V_{CMRFG} = 1.5V$ , and calculate the following formula :

$$I_{FG} = \frac{1}{2} \times I_{FG}'$$

- $V_{OFFG}$   
Measure the  $R_{LO}$  pin output voltage when  $V_{CMRFG} = 1.5V$ , and calculate the following formula :

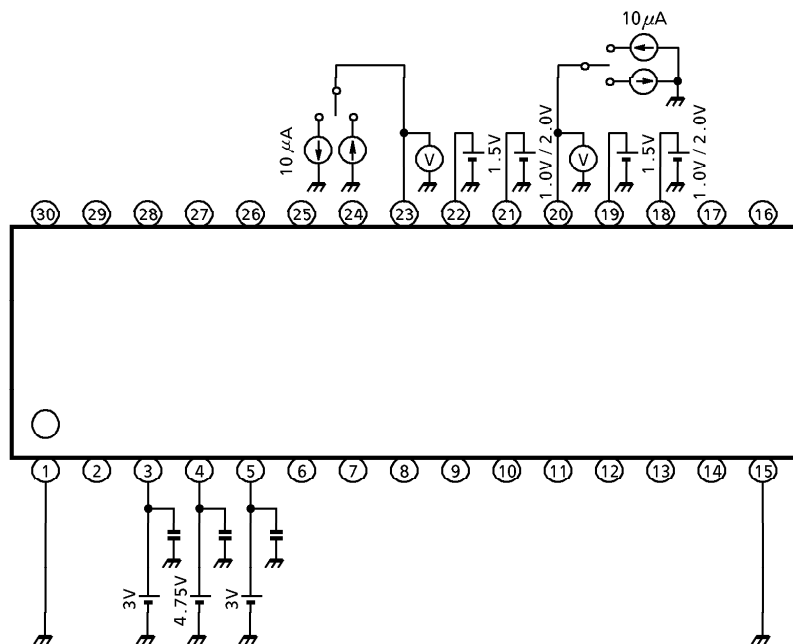
$$V_{OFFG} = V_{RLO} - 1.5$$

11.  $G_{VFG}$ 

- $G_{VFG}$   
 $V_{RLP} = 1.5V$ , input signals

$f_{FG} = 1kHz$ ,  $V_{FG} = 50mV_{p-p}$  between RLP and RLM, and measure  $V_{RLO}$  in this case.

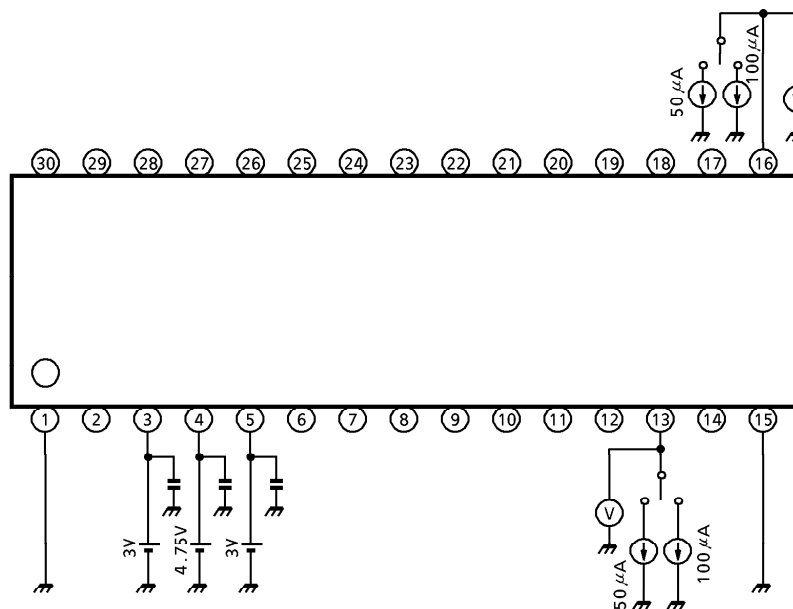
$$G_{VFG} = 20 \log \frac{V_{RLO}}{0.05} \text{ [dB]}$$

12.  $V_{\text{sat-FG}}(\text{H})$ ,  $V_{\text{sat-FG}}(\text{L})$ 

- $V_{\text{sat-FG}}(\text{H})$   
Input  $V_{\text{RLP}} = 1.5\text{V}$ ,  
 $V_{\text{RLM}} = 1.0\text{V}$ , measure the  
 $R_{\text{LO}}$  pin voltage when  
 $I_{\text{O}} = 10\mu\text{A}$  (source current),  
and calculate the following  
formula :

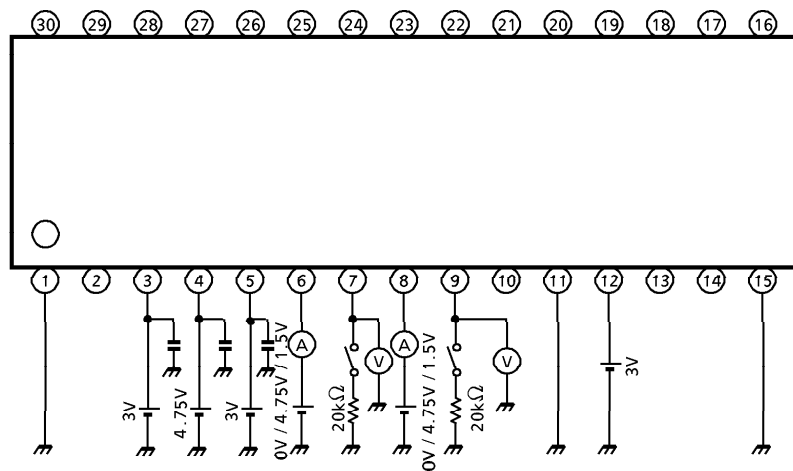
$$V_{\text{sat-FG}}(\text{H}) = 3.0 - V_{\text{RLO}} [\text{V}]$$

- $V_{\text{sat-FG}}(\text{L})$   
Input  $V_{\text{RLP}} = 1.5\text{V}$ ,  
 $V_{\text{RLM}} = 2.0\text{V}$  and measure the  
 $R_{\text{LO}}$  pin voltage when  
 $I_{\text{O}} = 10\mu\text{A}$  (sink current).

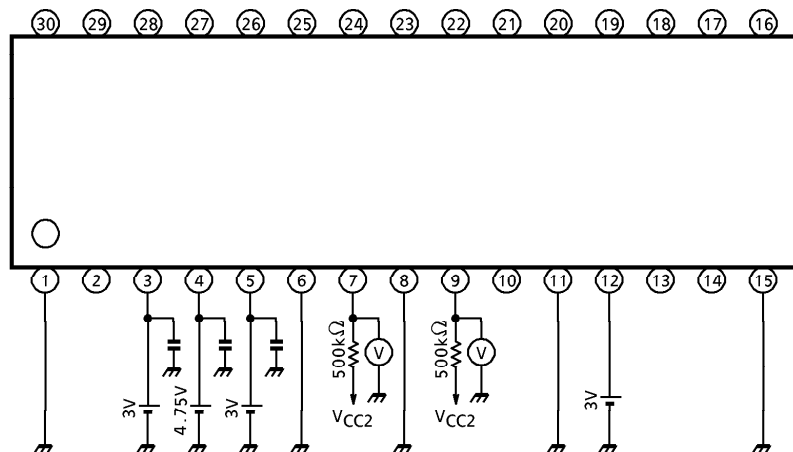
13.  $R_{\text{IN}}$ 

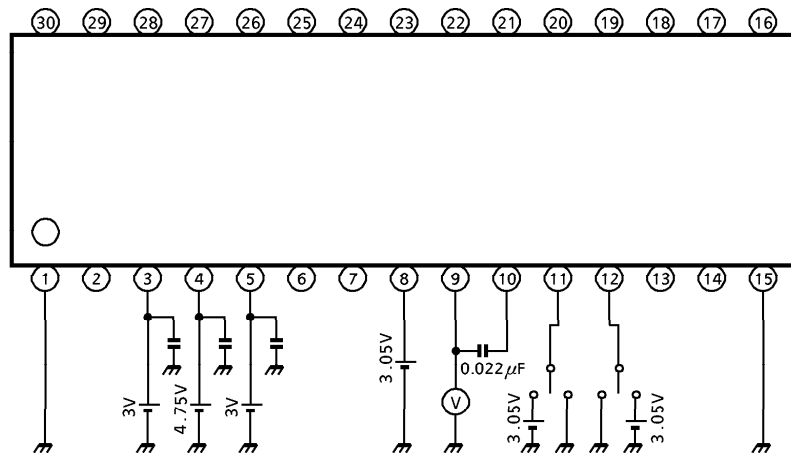
- $R_{\text{IN}}$   
Measure the  $V_{\text{TOPIN}}$ ,  $V_{\text{ENDIN}}$   
at the time  $50\mu\text{A} / 100\mu\text{A}$   
current flows from TOPIN /  
ENDIN pin, and calculate the  
following formula :  
$$R_{\text{IN}} = \frac{V(50\mu\text{A}) - V(100\mu\text{A}) - 0.007}{50\mu\text{A}} [\Omega]$$

\* The 7mV in the formula  
represents the  $V_{\text{BE}}$  change of  
the internal  $\text{Tr.}$  at the time  
of  $50\mu\text{A} / 100\mu\text{A}$ .

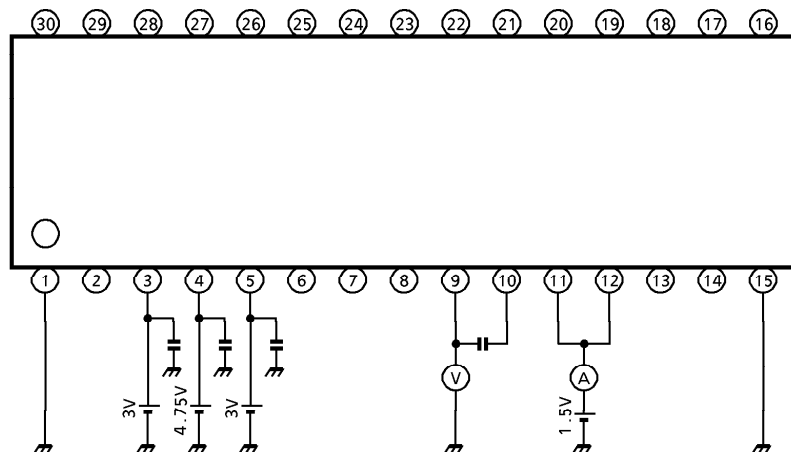
14.  $V_{CMRB}$ ,  $I_B$ ,  $V_{OB(H)}$ 

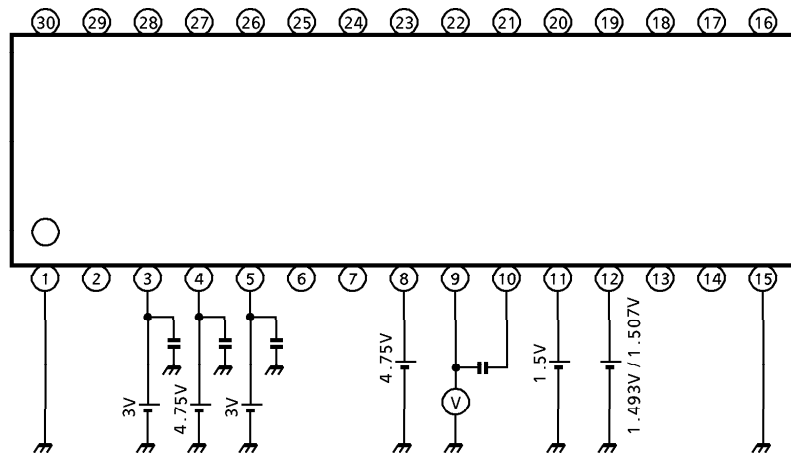
- $V_{CMRB}$   
Input  $V_{BIN} = 0V / 4.75V$  and measure BOUT pin voltage.
- $I_B$   
 $V_{BIN} = 1.5V$
- $V_{OB(H)}$   
Input  $V_{BIN} = 4.75V$  and connect  $20k\Omega$  (against GND) to BOUT pin.

15.  $V_{OB(L)}$ 

16.  $V_{CMRBL}$ 

- $V_{CMRBL}$   
Check BOUT2 pin : L when  $V_{RFB} = 3.05V$ ,  $V_{RSB} = 0V$ .  
Check BOUT2 pin : L when  $V_{RFB} = 0V$ ,  $V_{RSB} = 3.05$ .

17.  $I_{BL}$ 

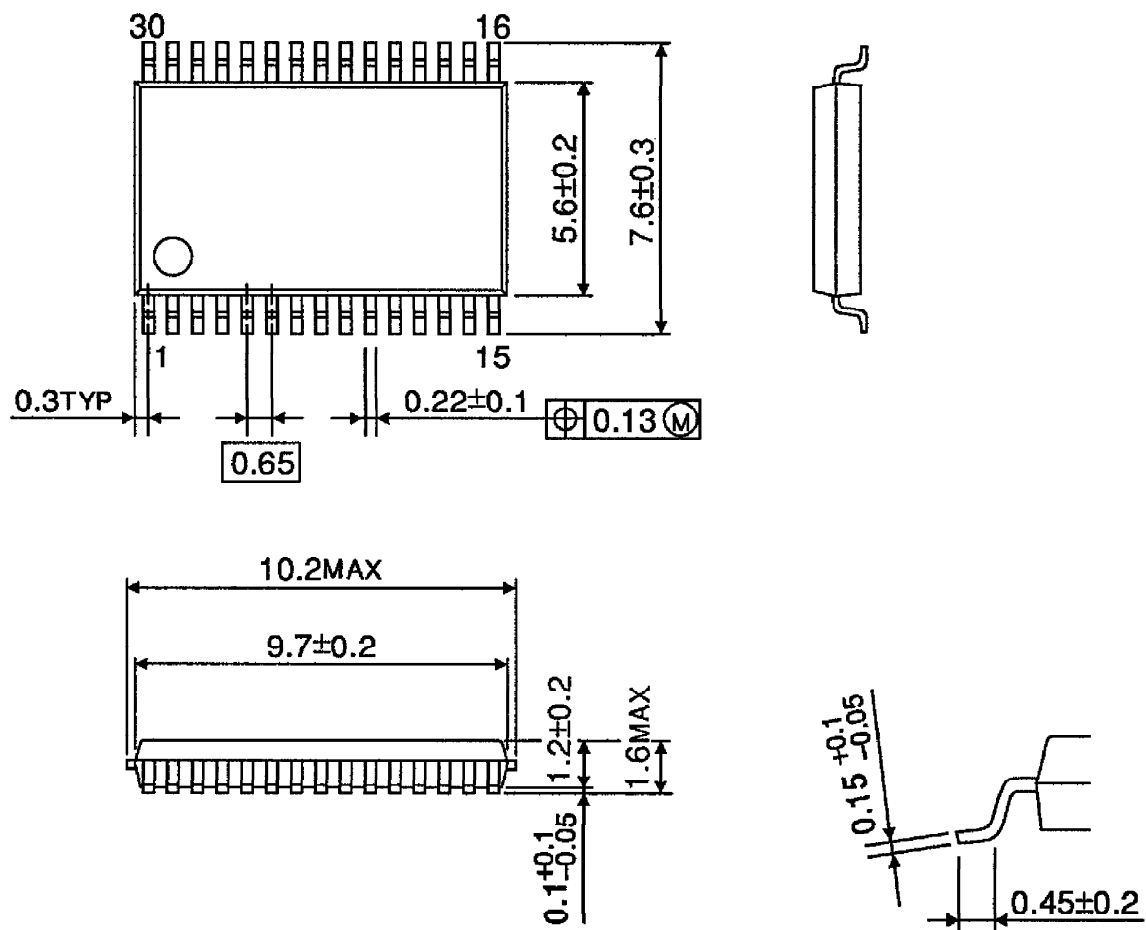
18.  $V_{OFBL}$ 

- $V_{OFBL}$   
 Input  $V_{RSB} = 1.5V$ ,  
 $V_{RFB} = 1.5V \pm 7mV$ , and check  
 the switching of BOUT2 pin  
 output function.  
 BOUT2 : H when  
 $V_{RFB} = 1.493V$ .  
 BOUT2 : L when  
 $V_{RFB} = 1.507V$ .



OUTLINE DRAWING  
SSOP30-P-300-0.65

Unit : mm



Weight : 0.17g (Typ.)